

The initial stages of cave formation: Beyond the one-dimensional paradigm

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Abstract

The solutional origin of limestone caves was recognized over a century ago, but the short penetration length of an undersaturated solution made it seem impossible for long conduits to develop. This is contradicted by field observations, where extended conduits, sometimes several kilometers long, are found in karst environments. However, a sharp drop in the dissolution rate of CaCO_3 near saturation provides a mechanism for much deeper penetration of reactant. The notion of a “kinetic trigger” - a sudden change in rate constant over a narrow concentration range - has become a widely accepted paradigm in speleogenesis modeling. However, it is based on one-dimensional models for the fluid and solute transport inside the fracture, assuming that the dissolution front is planar in the direction perpendicular to the flow. Here we show that this assumption is incorrect; a planar dissolution front in an entirely uniform fracture is unstable to infinitesimal perturbations and inevitably breaks up into highly localized regions of dissolution. This provides an alternative mechanism for cave formation, even in the absence of a kinetic trigger. Our results suggest that there is an inherent wavelength to the erosion pattern in dissolving fractures, which depends on the reaction rate and flow rate, but is independent of the initial roughness. In contrast to one-dimensional models, two-dimensional simulations indicate that there is only a weak dependence of the breakthrough time on kinetic order; localization of the flow tends to keep the undersaturation in the dissolution front

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above the threshold for non-linear kinetics.

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1 1. Introduction

2 The notion that caves result from dissolution by an aqueous solution of
3 carbon dioxide was already present in the works of Lyell and Thirria in the
4 1830s (Shaw, 2000), but it was not until 100 years later that these ideas
5 were developed mathematically. A quantitative model of the dissolution of a
6 single limestone fracture was developed by Weyl (1958), taking into account
7 chemical kinetics and solute transport. His theory led to the paradoxical con-
8 clusion that water flowing through a limestone fracture becomes saturated
9 with calcium ions over length scales of the order of centimeters, so that lime-
10 stone caves should not exist at all (White and Longyear, 1962). A possible
11 resolution of this paradox was proposed by White (1977), who noted that
12 the existence of large cave systems may be explained by the sharp drop in
13 the dissolution rate of CaCO_3 near saturation; this is frequently referred to
14 as the “kinetic trigger” mechanism in the speleogenesis literature. Dissolu-
15 tion of blocks of calcite under laboratory conditions confirm that there is a
16 rapid drop in reaction rate near saturation, apparently because of impuri-
17 ties in natural calcite (Plummer et al., 1976; Dreybrodt, 1990; Palmer, 1991;
18 Svensson and Dreybrodt, 1992).

19 Several calculations (Dreybrodt, 1990; Palmer, 1991; Groves and Howard,
20 1994; Dreybrodt, 1996) have shown that the kinetic trigger hypothesis al-
21 lows for the development of deep conduits, but they are all based on a one-
22 dimensional model of fracture dissolution. The initial fissure is approximated
23 by two parallel planes, and all the relevant variables (aperture, fluid volume
24 flux, and solute concentration), depend only on the distance from the inlet
25 (see Fig. 1). However real fractures are never one-dimensional; in this paper
26 we show that even a tiny variability in fracture aperture inevitably leads to
27 an instability at the reaction front, which then breaks up into highly local-
28 ized regions of dissolution. Thus, the premise that a smooth fracture will
29 open uniformly across its width, which underlies current models of speleoge-
30 nesis, is faulty. A correct description of fracture dissolution must include the
31 variation in aperture across the lateral direction as well.

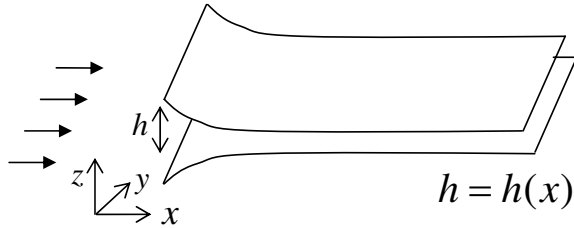


Figure 1: Dissolution of a one-dimensional fracture; fluid flow is in the x direction and the fracture surfaces dissolve in the normal (z) direction. The fracture surfaces can be assumed to be located at $\pm h/2$.

32 2. Breakthrough times in one and two dimensions

33 In this paper we reevaluate the standard mathematical model for the early
 34 stages of cave formation, describing the dissolution of a calcite fracture by
 35 surface water draining through it to a lower-lying water table. We analyze the
 36 coupled equations for fluid flow, reactant transport and surface dissolution
 37 to show that the evolution of the fracture aperture is an inherently two-
 38 dimensional process, even when the initial aperture field is spatially uniform.

39 2.1. Flow and transport: 1D model

40 In studies of fracture dissolution, and particularly in theoretical investi-
 41 gations of cave formation, a one-dimensional model of a single fracture is
 42 frequently used (e.g. Dreybrodt, 1990; Groves and Howard, 1994; Dreybrodt,
 43 1996; Dijk and Berkowitz, 1998). In this model, schematically represented in
 44 Fig. 1, the fracture aperture $h(x, t)$ is assumed to depend on a single spatial
 45 variable, the distance from the inlet. The flow rate, $q(t)$, is then independent
 46 of position,

$$q(t) = \frac{\Delta p}{r(t)}, \quad r(t) = 12\mu \int_0^L \frac{dx}{h(x, t)^3}, \quad (1)$$

47 where Δp is the difference between the inlet and outlet pressures, L is the
 48 fracture length along the flow (x) direction, and r is the integrated flow
 49 resistivity.

50 The concentration of Ca^{2+} ions in the fracture, $c(x, t)$, is described by a
 51 convection-diffusion equation

$$q \frac{dc}{dx} - \frac{d}{dx} \left(h D_{xx} \frac{dc}{dx} \right) = 2R(c), \quad (2)$$

52 where D_{xx} is the dispersion coefficient and $R(c)$ is the reactive flux from
 53 the dissolving calcite. The factor of two in the dissolution rate comes from
 54 combining erosion at the upper and lower fracture surfaces. It is assumed that
 55 the inlet stream is pure water, $c(0, t) = 0$, and the outlet stream is a saturated
 56 solution, $c(L, t) = c_{sat}$. Finally, the aperture evolution is determined from
 57 the local reactive flux

$$c_{sol} \frac{dh}{dt} = 2R(c) \quad (3)$$

58 where c_{sol} is the molar concentration of the solid phase.

59 *2.2. Dissolution and breakthrough: 1D model*

60 Early theories of karstification assumed linear dissolution kinetics (Weyl,
 61 1958; White and Longyear, 1962),

$$R(c) = k(c_{sat} - c). \quad (4)$$

62 In this case the undersaturation decays exponentially into the fracture, $c_{sat} -$
 63 $c \sim e^{-x/l_p}$, with a penetration length,

$$l_p = q/2k. \quad (5)$$

64 Dissolution is restricted to a narrow region near the inlet, $x \sim l_p$, which limits
 65 the growth of conduits. In fractured carbonate formations l_p is typically less
 66 than a meter (White and Longyear, 1962; Atkinson, 1968; Dreybrodt, 1990).
 67 White (1977) proposed that field observations of extended conduits in karst
 68 environments, sometimes several kilometers long, might best be explained by
 69 a sharp drop in mineral dissolution rate as saturation is approached. This
 70 “kinetic trigger” mechanism can be modeled as a switch from linear to higher
 71 order kinetics at a threshold concentration c_{th} :

$$R(c) = \begin{cases} k(c_{sat} - c), & c < c_{th} \\ k_n(c_{sat} - c)^n, & c > c_{th}. \end{cases} \quad (6)$$

72 A non-linear kinetic law ($n > 1$ in Eq. (6)) results in an algebraic decay of
 73 the concentration profile at large distances from the inlet, $c_{sat} - c \sim x^{1/1-n}$,

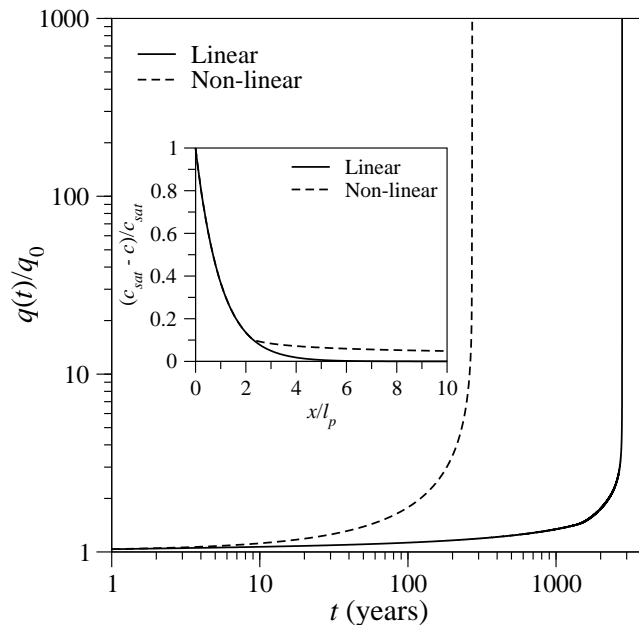


Figure 2: One-dimensional dissolution of a 20m fracture with a uniform initial aperture $h(x) = h_0 = 0.2\text{mm}$; $\text{Pe} = 100$ and $\text{Da} = 5 \times 10^{-4}$. The volumetric flux $q(t)$, scaled by the initial flux in the fracture $q(0)$, is shown for linear and non-linear kinetics. The inset shows the concentration profile from Eqs. (2) and (6), with $c_{th} = 0.9c_{sat}$.

74 and the fracture opens over its entire length. Concentration profiles for linear
 75 and non-linear kinetics are illustrated in the inset to Fig. 2. In these (and
 76 subsequent) calculations we take typical parameter values for calcite disso-
 77 lution: $n = 4$, $k = 2.5 \times 10^{-5}\text{cms}^{-1}$ and $c_{sat} = 2 \times 10^{-6}\text{Mcm}^{-3}$ (Dreybrodt,
 78 1996). The reaction rate $k_4 = k(c_{sat} - c_{th})^{-3}$ is adjusted so that $R(c)$ is con-
 79 tinuous at $c = c_{th}$, and the threshold concentration itself was set to $0.9c_{sat}$.
 80 The molar concentration in the solid phase was taken as 0.027Mcm^{-3} , based
 81 on the mass density of pure calcite.

82 In this paper we take the initial fracture aperture $h_0 = 0.2\text{mm}$, which
 83 means that the product of Péclet number, $\text{Pe} = q_0/D$, and Damköhler num-
 84 ber, $\text{Da} = kh_0/q_0$, is about 0.05. Here q_0 is the initial value of the volumetric
 85 flux in the fracture and the solute diffusion constant $D \approx 10^{-5}\text{cm}^2\text{s}^{-1}$.

86 Figure 2 shows typical breakthrough curves for linear and non-linear ki-
 87 netics, obtained by solving Eqs. 1–3 numerically (see Appendix A for de-
 88 tails). The volumetric flux in the initial fracture is about $10^{-3}\text{cm}^2\text{s}^{-1}$, corre-
 89 sponding to an hydraulic gradient of 0.01. The penetration length, $l_p \approx 20\text{cm}$,

90 is much less than the length of the fracture ($L = 20\text{m}$). Thus with linear
 91 kinetics the opening of the fracture aperture is slow, with the breakthrough
 92 time scaling exponentially with the length of the fracture. Breakthrough
 93 occurs much earlier in the non-linear case, because the slower kinetics allow
 94 a deeper penetration of reactant into the fracture (White, 1977; Dreybrodt,
 95 1990). The time scale for dissolution can be characterized by the growth
 96 of the fracture aperture at the inlet, $h(0, t) = h_0 + 2ktc_{sat}/c_{sol}$, which is in-
 97 dependent of the kinetic model and the dimensionality of the fracture. We
 98 define

$$\tau = h_0 c_{sol} / 2k c_{sat} \quad (7)$$

99 as the time it takes for the initial fracture aperture at the inlet to double.
 100 For an 0.2mm fracture, $\tau = 5.4 \times 10^6\text{s}$ or approximately 0.17 years.

101 2.3. Flow and transport: 2D model

102 Although one-dimensional models are simple and mathematical tractable,
 103 laboratory experiments (Durham et al., 2001; Gouze et al., 2003; Detwiler et al.,
 104 2003) have shown that in most cases fracture dissolution is non-uniform in
 105 the direction transverse to the flow, with highly localized two-dimensional
 106 dissolution patterns (Hanna and Rajaram, 1998). The non-linear dynam-
 107 ics underlying this more complicated behavior can be probed using *depth-*
 108 *averaged* models (Cheung and Rajaram, 2002; Detwiler and Rajaram, 2007),
 109 in which the fluid velocity and reactant concentration are still averaged over
 110 the fracture aperture (z direction in Fig. 1), but can vary in the lateral
 111 (y) direction. Coupled equations for the fluid volume flux $\mathbf{q}(x, y, t)$, depth-
 112 averaged concentration of dissolved solids $c(x, y, t)$, and aperture $h(x, y, t)$
 113 are solved simultaneously:

$$\begin{aligned} \nabla \cdot \mathbf{q} &= 0, \quad \mathbf{q} = -\frac{h^3}{12} \frac{\nabla p}{\mu}, \\ \mathbf{q} \nabla \cdot c - \nabla \cdot (h \mathbf{D} \cdot \nabla c) &= 2R(c) \\ c_{sol} \partial_t h &= 2R(c), \end{aligned} \quad (8)$$

114 where $\mathbf{D}(h)$ is the solute dispersion tensor. Details of our numerical solution
 115 of Eq. (8) can be found in Appendix A.

116 In Sec. 3 we will show mathematically that the one-dimensional dissolu-
 117 tion profiles described by Eqs. (1)–(3), are unstable. Uniform concentration
 118 profiles inevitably break down into more complex dissolution patterns, which
 119 can be described by Eq. (8). Simulations based on Eq. (8) have proven to be

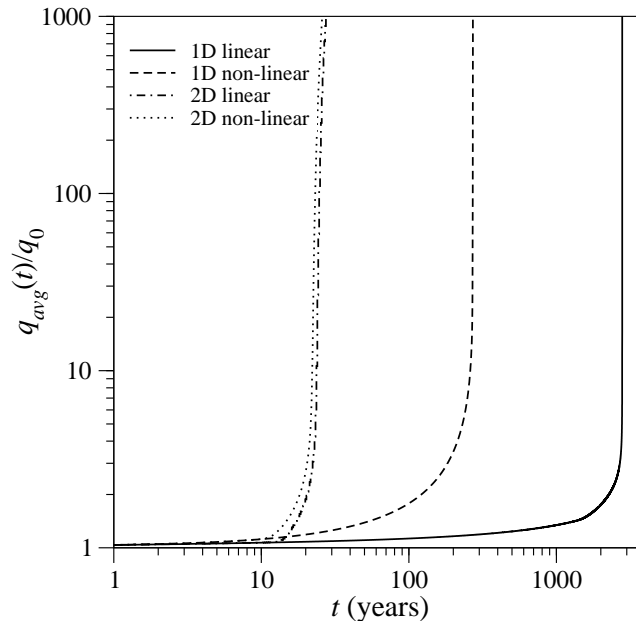


Figure 3: Dissolution of a smooth fracture $20\text{m} \times 10\text{m} \times 0.2\text{mm}$; the parameters $\text{Pe} = 100$ and $\text{Da} = 5 \times 10^{-4}$. One-dimensional simulations of the volumetric flux $q(t)$ are compared with two-dimensional simulations of the average flux $q_{avg}(t) = W^{-1} \int_0^W q_x(x, y, t) dt$. The fluxes are scaled by the initial flux in the fracture q_0 .

120 successful in predicting the large scale dissolution patterns in artificial frac-
 121 tures (Detwiler and Rajaram, 2007), although at small scales, comparable to
 122 the correlation length in the aperture field, the dissolution is more uniform
 123 than the experimental observations. For such fine details three-dimensional
 124 simulations are necessary, including the variation in flow and concentration
 125 fields across the aperture (Szymczak and Ladd, 2009).

126 2.4. Dissolution and breakthrough: 2D model

127 We repeated the one-dimensional simulations shown in Fig. 2 using a
 128 two-dimensional fracture, $20\text{m} \times 10\text{m}$, superimposing a small random aper-
 129 ture field, with a variance $\sigma = 20\text{nm}$, over the original uniform aperture
 130 (0.2mm). Time-dependent flow rates from 1D and 2D simulations are com-
 131 pared in Fig. 3. Two-dimensional simulations show a significant reduction
 132 in the breakthrough time in comparison with 1D models, in agreement with
 133 earlier results (Hanna and Rajaram, 1998; Szymczak and Ladd, 2009). In-
 134 terestingly, the added spatial dimension has a larger effect on the break-

135 through time than the kinetic trigger. In the one-dimensional simulations,
 136 non-linear kinetics reduces the breakthrough time by an order of magnitude,
 137 from 2800 years to 270 years. However, in the two-dimensional simulations,
 138 the breakthrough time is less than 30 years, regardless of the kinetics. In
 139 fact the non-linear kinetics makes only a small difference here, reducing the
 140 breakthrough time from about 28 years (linear) to 26 years (non linear).

141 The reason why dimensionality is crucial can be seen in the concentra-
 142 tion maps shown in Fig. 4. The initially planar dissolution front breaks down
 143 into increasingly focused regions of dissolution, which rapidly advance into
 144 the fracture, causing breakthrough at much earlier times than in the homoge-
 145 neous (one-dimensional) case (Hanna and Rajaram, 1998; Szymczak and Ladd,
 146 2009). Flow focusing keeps the concentration in the advancing front high,
 147 above the threshold for non-linear kinetics; this explains the relatively small
 148 difference in breakthrough times in the two-dimensional simulations.

149 In the course of extensive numerical investigations of fracture dissolution,
 150 we noticed that a planar dissolution front was always unstable if the fracture
 151 length, L , was sufficiently large in comparison with the penetration length,
 152 l_p . Our simulations suggested that on geophysical scales, where $L \gg l_p$
 153 dissolution will be inherently unstable. Mathematical analysis, described
 154 in Appendix C, confirms that fracture dissolution is always two-dimensional,
 155 and cannot be usefully approximated by one-dimensional models.

156 3. Instability of dissolution in a uniform aperture fracture

157 The stability of a uniform dissolution front can be investigated from a
 158 minimal model, assuming linear kinetics, and neglecting the dispersive term
 159 in Eq. (8):

$$\begin{aligned}
 \nabla \cdot \mathbf{q} &= 0, & \mathbf{q} &= -\frac{h^3}{12} \frac{\nabla p}{\mu}, \\
 \mathbf{q} \cdot \nabla c &= 2k(c_{sat} - c) \\
 c_{sol} \partial_t h &= 2k(c_{sat} - c).
 \end{aligned}
 \tag{9}$$

160 In Sec. 2.4 we showed (Fig. 3) that once a two-dimensional model of frac-
 161 ture dissolution is adopted, variations in kinetic order are of only quantita-
 162 tive rather than qualitative importance to the predicted breakthrough time.
 163 Moreover, on the scale of penetration length, the ratio of the diffusive flux,
 164 Dhc/l_p^2 , to the convective flux, qc/l_p , is of the order of Pe^{-1} Da. This pa-
 165 rameter is small in typical limestone fractures, as shown by a consideration
 166 of fracture apertures and hydraulic gradients (Appendix B); thus Eq. (9)

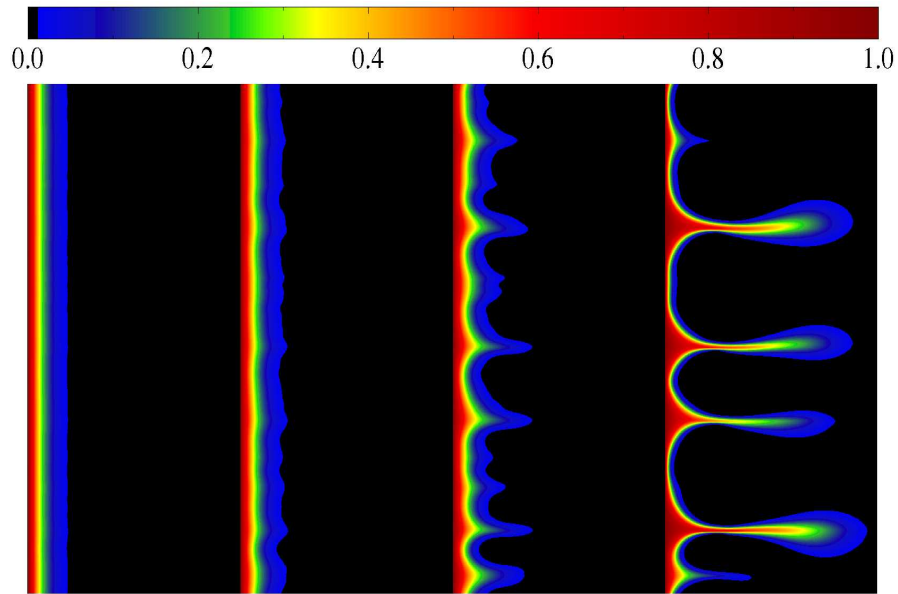


Figure 4: Concentration profiles in a dissolving fracture (color online). Contour plots of the normalized undersaturation, $(c_{sat} - c)/c_{sat}$, are plotted at successive times (from left to right); $t = 25\tau$, $t = 50\tau$, $t = 75\tau$, and $t = 100\tau$. The flow direction is from left to right; the Péclet and Damköhler numbers are $Pe = 100$ and $Da = 5 \times 10^{-4}$. A video of the complete time sequence is accessible by clicking on the Figure (online version).

167 contains all the essential physics of the instability. However, in gypsum karst
 168 the reaction rate is much higher ($Da > 1$) and the penetration length equiva-
 169 lently smaller; in this case diffusive flux is significant and should be included,
 170 as in Eq. (C.14).

171 In the initial stages of dissolution, when the penetration length is much
 172 less than the length of the fracture, $l_p \ll L$, the one-dimensional flow and
 173 concentration fields are essentially time independent,

$$q(t) \approx q_0 = -\frac{h_0^3 p'_0}{12\mu}, \quad c(x, t) \approx c_0(x) = c_{sat}(1 - e^{-x/l_p}). \quad (10)$$

174 The pressure gradient $p'_0 = \partial_x p$ is constant far from the inlet and q is inde-
 175 pendent of x by continuity; the subscript 0 is used to denote initial values.
 176 The aperture grows linearly in time, with a rate that decays exponentially
 177 with the distance from the inlet,

$$h(x, t) = h_0 \left(1 + \frac{te^{-x/l_p}}{\tau} \right). \quad (11)$$

178 The flow rate and concentration field remain constant in time until the pene-
 179 tration is deep enough to perturb the far field pressure gradient and increase
 180 the flow rate in the fracture.

181 However, an initially smooth fracture does not evolve according to Eq. (11);
 182 in fact the one-dimensional solution is exponentially unstable to perturba-
 183 tions in h , $\delta h(x, y, t) \sim e^{\omega t}$, which rapidly outrun the uniform front suggested
 184 by Eq. (11). A linear stability analysis of Eqs. (9) leads to a dispersion re-
 185 lation for the growth rate ω as a function of the wavelength of the pertur-
 186 bation λ , as shown in Fig. 5. The particulars of the analysis can be found
 187 in Appendix C. Here we just mention one subtle but important detail; the
 188 base state, Eq. (11), is itself time-dependent. The stability of nonautonomous
 189 systems is in general a very difficult problem (Farrell and Ioannou, 1996);
 190 here however we follow a relatively simple, approximate approach (Tan and Homsy,
 191 1986) in which the base state is frozen at a particular time and the growth rate
 192 is determined as if the base state were time-independent (the quasisteady-
 193 state approximation). The dispersion curve in Fig. 5 was obtained by freezing
 194 the base state at $t_0 = 0$. We will examine this approximation in more detail
 195 in Sec. 4.

196 The most striking result of the linear stability analysis is that there is
 197 a maximal growth rate, $\omega_{max} = 0.79\tau^{-1}$, at a wavelength $\lambda_{max} = 4.74l_p$

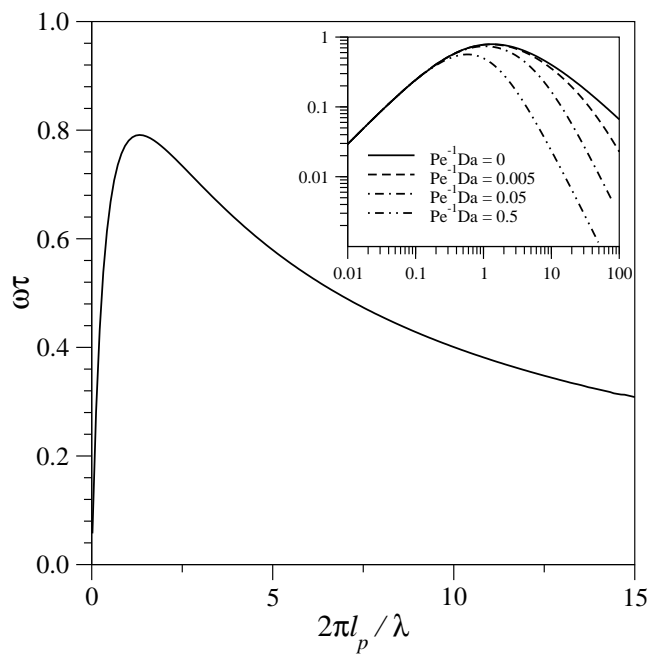


Figure 5: Growth rate of the instability in a smooth fracture. The time scale $\tau = h_0/2k\gamma$. The inset figure shows the growth rate over a larger range of wavelengths, including the effects of lateral diffusion as measured by the ratio $\text{Pe}^{-1} \text{Da}$.

198 (Fig. 5). An individual fracture can therefore develop a strongly heteroge-
 199 neous permeability during dissolution, with an inherent length scale that
 200 depends on the kinetics and flow rate (via l_p), but not the initial topogra-
 201 phy. Furthermore, there is no lower limit to the reaction rate for unstable
 202 dissolution. Only the wavelength and penetration depth are affected, scaling
 203 with the inverse of the Damköhler number.

204 In laboratory experiments it is frequently the case that the sample length
 205 is less than l_p , in which case uniform dissolution is observed (Fredd and Fogler,
 206 1998). But on scales of geophysical relevance, dissolution of carbonate rocks
 207 will always be unstable; calcite for example would have characteristic wave-
 208 lengths $\lambda_{max} \sim 1\text{m}$, while in dolomite $\lambda_{max} \sim 10\text{m}$. It is worth noting that
 209 the instability in the dissolution front continues to grow in systems confined
 210 to widths smaller than l_p , although at a reduced rate. Figure 5 shows that
 211 there is a long tail to the dispersion relation at short wavelengths, with a
 212 weak power-law dependence $\omega \sim \lambda$. Thus in narrow fractures, where the
 213 width $W < \lambda_{max}$, a single channel develops which contains all the flow in the
 214 fracture.

215 The instability analysis in Appendix C can be generalized to include lat-
 216 eral diffusion (in the y direction), which is expected to play a more important
 217 role in the dynamics than axial diffusion because axial transport is usually
 218 convection dominated. On scales comparable to the penetration length, the
 219 relative magnitude of diffusive and convective fluxes is given by the param-
 220 eter Pe^{-1}Da , as can be seen in Eq. (C.14). The inset to Fig. 5 shows the
 221 dispersion relation for several different values of the ratio Pe^{-1}Da . Lateral
 222 diffusion reduces the growth rate of short wavelength perturbations and shifts
 223 λ_{max} towards longer wavelengths. However, it does not prevent the instability
 224 developing and the growth rate remains positive for all wavelengths.

225 4. Numerical simulations of the instability

226 We have confirmed the key predictions of the instability analysis by nu-
 227 merically solving Eqs. (8) with linear reaction kinetics. In comparison with
 228 the minimal model considered in the previous section, we have here in-
 229 cluded solute dispersion and the effect of diffusion on the dissolution kinetics,
 230 Eq. (A.5). Beginning from a uniform fracture ($h_0 = 0.2\text{mm}$), with a small
 231 random roughness superimposed ($\sigma = 10^{-4}h_0$), we see a single sinusoidal
 232 mode developing in the dissolution front, as illustrated in Fig. 4. The wave-
 233 length and front thickness are inversely proportional to Damköhler number,

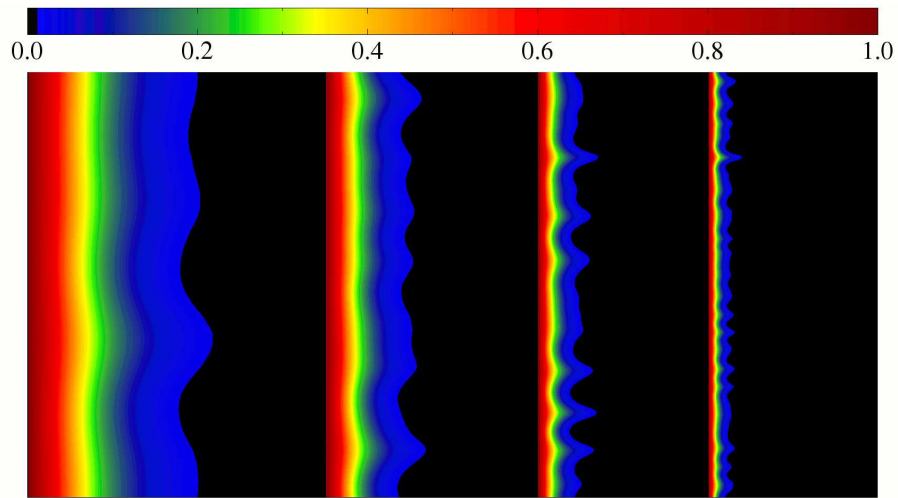


Figure 6: Concentration profiles of a dissolving fracture (color online). Contour plots of the normalized undersaturation, $(c_{sat} - c)/c_{sat}$, are plotted for different Damköhler numbers (from left to right); $Da = 1.25 \times 10^{-4}$, 2.5×10^{-4} , 5.0×10^{-4} , and $Da = 10^{-3}$. The product of Péclet and Damköhler numbers is 0.05 in each case. The flow is from left to right and the time $t = 50\tau$. The variance in the aperture was reduced to $10^{-5}h_0$ so that the sinusoidal perturbations in the front are more easily visible at larger Da .

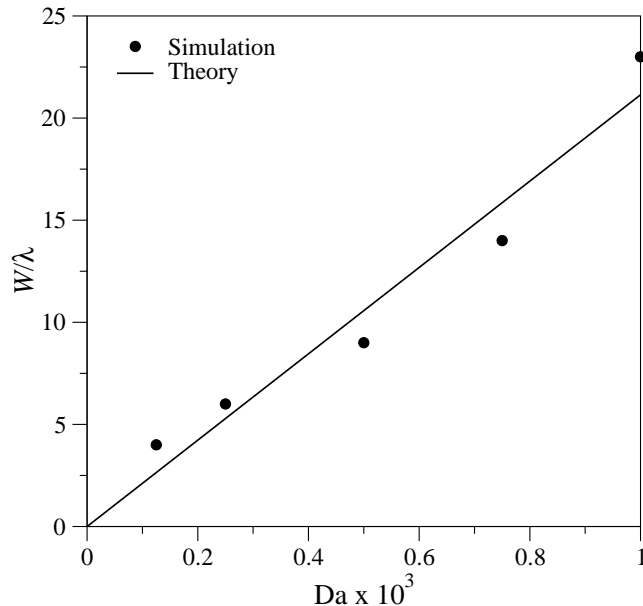


Figure 7: Wavelength dependence of the dominant mode as a function of Damköhler number, Da . The solid circles show the number of wavelengths in a system of fixed width $W = 10\text{m}$, determined by a Fourier analysis of the concentration profile. The solid line is the theoretical prediction based on wavelength of the fastest-growing mode, $\lambda_{max} = 4.74l_p$

234 as shown in Fig. 6, confirming that penetration length, $l_p = h_0/2 Da$, is the
 235 only important length scale in the early stages of dissolution. Concentration
 236 profiles, such as those illustrated in Fig. 6, can be Fourier transformed in the
 237 lateral (y) direction to determine the wavelength of the instability as a func-
 238 tion of the Damköhler number. An analysis of the number of wavelengths,
 239 W/λ_{max} , in a system of width $W = 10\text{m}$ confirms that the fastest growing
 240 modes have a wavelength close to the theoretical prediction $\lambda_{max} = 4.74l_p$
 241 ($l_p = h_0/2 Da$), as can be seen in Fig. 7.

242 The growth rates of the instability can be obtained by analyzing fluctu-
 243 ations in concentration field,

$$\Delta_c(x, t) = \sqrt{\sum_y [c(x, y, t) - \bar{c}(x, t)]^2}. \quad (12)$$

244 We take the maximum value of $\Delta_c(x, t)$ along the fracture, $\Delta_c(t)$, as a mea-
 245 sure of the amplitude of the perturbation at time t . Results for $\Delta_c(t)$,

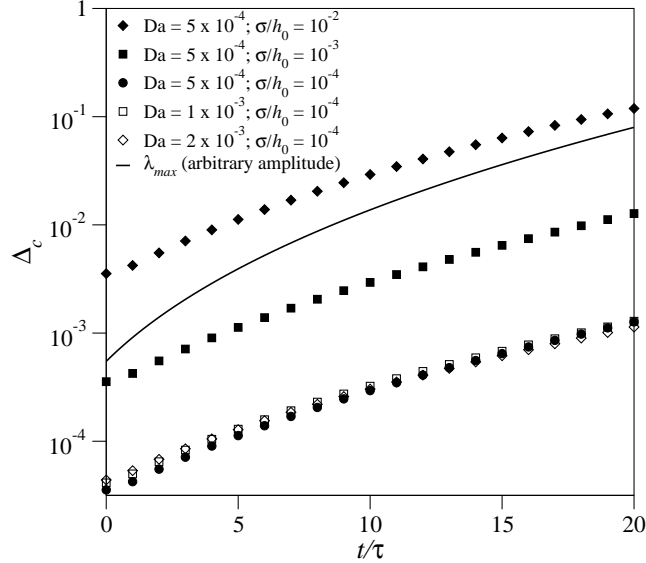


Figure 8: Time-dependent fluctuations in concentration for different values of the Damköhler number, Da , and roughness, σ/h_0 ; σ is the variance in the aperture. The solid line shows the growth of the mode with an initial wavelength of λ_{max} , based on a numerical integration of the linearized equation, Eq. (C.7)

246 presented in Fig. 8, confirm that the instability is initiated as soon as the
 247 undersaturated solution enters the fracture, and that the growth is indeed
 248 approximately exponential in time. In reduced time units (t/τ) the growth
 249 rate is independent of Damköhler number and roughness; only the amplitude
 250 of the fluctuations is affected by the initial variability in the fracture aper-
 251 ture. For comparison, we also plot the solution of the linearized initial value
 252 problem, Eq. (C.7), which includes the time dependence of the base aperture
 253 field, Eq. (11). We take the eigenfunction, Eq. (C.12), corresponding to the
 254 fastest-growing eigenmode, $u = 2\pi l_p/\lambda_{max}$, as the initial condition. Initially,
 255 fluctuations in a random aperture field grow more slowly than the fastest-
 256 growing mode, but after a while ($\approx 10\tau$) a single mode is dominant, and the
 257 growth rates become similar.

258 The linear stability analysis summarized in Fig. 5 predicts an exponential
 259 growth of the instability. On the other hand, the numerical results in Fig. 8
 260 indicate that the growth is less than exponential. This is because the time
 261 dependence of the base state weakens the instability as the fracture inlet
 262 opens up. Figure 9 shows the dispersion relation obtained from the quasi-

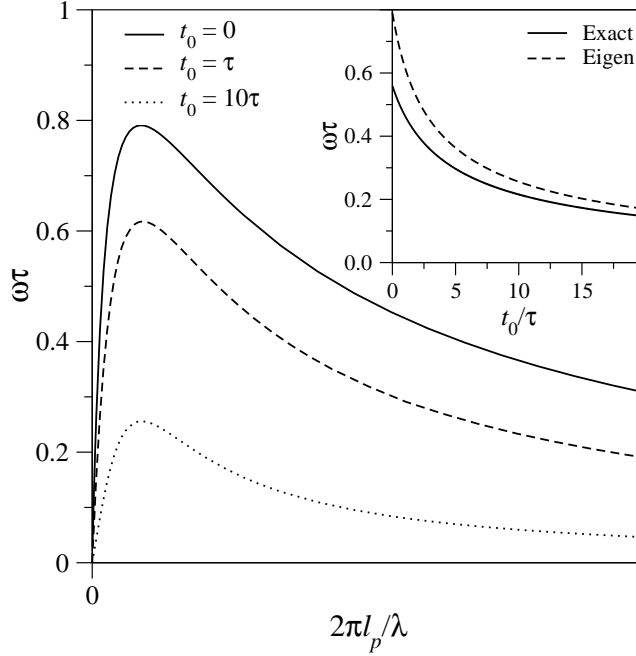


Figure 9: Growth rate of the instability in a smooth fracture with the base state frozen at different times: $t_0 = 0$ (solid line), $t_0 = \tau$ (dashed line), and $t_0 = 10\tau$ (dotted line). The inset figure shows the growth rate of the mode with an initial wavelength of $\lambda_{max} = 4.74l_p$, for different times: the linearized solution (solid line), including the time-dependence of the base state, Eq (C.7), is compared with the eigensolution analogous to Eq. (C.13) (dashed line)

263 steady state approximation, Eq. (C.9), for different base states, frozen at
 264 $t_0 = 0$ (as in Fig. 5), $t_0 = \tau$, and $t_0 = 10\tau$; the growth rate is reduced
 265 across the whole spectrum of wavelengths as time goes on. However, the
 266 peak growth rate remains at almost the same wavelength, independent of
 267 time, so a single mode ($\lambda \approx \lambda_{max}$) predominates until the onset of non-linear
 268 growth.

269 The quasi-steady-state approximation, Eq. (C.9), used to calculate the
 270 dispersion curves in Fig. 9 (and Fig. 5) overestimates the growth rate when
 271 compared to the exact linearization in Eq. (C.7). The solid line in the inset
 272 to Fig. 9 show the growth rate of the mode with an initial wavelength of
 273 λ_{max} as a function of time; in essence the time derivative of the solid line in
 274 Fig. 8. The dashed line is the growth rate for the same wavelength (λ_{max})
 275 obtained by freezing the base state at successive moments of time. The

276 discrepancy is about 40% at $t_0 = 0$ and decreases thereafter, which agrees
277 with the observation of Tan and Homsy (1986) that the quasi-steady-state
278 approximation becomes exact in the long-time limit.

279 5. Discussion

280 The dissolution of an initially smooth fracture is one dimensional at early
281 times, but soon tiny random variations in fracture aperture lead to the devel-
282 opment of small perturbations in the front. The strong wavelength selection
283 (Fig. 5) means that after a fairly short time, approximately 1 – 2 years in our
284 model calcite fracture, a single mode becomes dominant, with a wavelength
285 that is about 5 times the penetration length (Fig. 7). As the perturbation
286 becomes stronger, distinct channels emerge from the front as shown in Fig. 4.
287 The embedded video (online version) illustrates this process dynamically; the
288 shorter channels are drained of reactant and cease to grow (Fredd and Fogler,
289 1998). Thus the spacing between long conduits is not determined solely by
290 the initial wavelength of the instability but also by the non-linear dynamics
291 of interacting channels. Eventually all the flow is localized within a few ac-
292 tive channels. In this paper we have shown that this is the expected behavior
293 on sufficiently large scales.

294 The notion of a kinetic trigger is an attractive explanation for the exist-
295 ence of long conduits in calcite formations, where there is an abundance of
296 evidence for a transition from linear to non-linear kinetics (Plummer et al.,
297 1976; Palmer, 1991; Svensson and Dreybrodt, 1992). However, in gypsum
298 there is good reason to think that the dissolution rate is roughly linear
299 in the undersaturation (Colombani and Bert, 2007; Colombani, 2008), al-
300 though it has been suggested that there is a changeover to non-linear kinet-
301 ics in natural gypsum as well (Jeschke et al., 2001). One-dimensional mod-
302 els of gypsum dissolution do not develop long conduits for typical fracture
303 apertures and flow rates (Raines and Dewers, 1997), unless a kinetic trigger
304 with a high-order ($n = 4$) rate law is again invoked (Dreybrodt et al., 2002;
305 Romanov et al., 2003).

306 The penetration length, Eq. (5), increases with time due to the increasing
307 flow rate, which introduces a feedback mechanism that produces the charac-
308 teristic upturn in $q(t)$ near breakthrough (Figs 2 and 3). In one-dimensional
309 models an increase in flow rate can only arise from the growth of the mean
310 aperture. However in two-dimensions *flow focusing* provides a mechanism for
311 a localized increase in flow rate; longer channels drain the flow from neigh-

312 boring regions of the fracture, promoting their own growth at the expense
313 of their neighbors (Fredd and Fogler, 1998; Hanna and Rajaram, 1998). The
314 process can be understood by considering the pressure fields in channels of
315 different lengths (Szymczak and Ladd, 2006). Given enough time, only a
316 single channel remains and at that point the flow focusing mechanism stalls;
317 the flow rate in the remaining channel can now only grow by extending its
318 length. Thus there is a maximum flow rate that a single channel can acquire
319 by flow focusing, $q_{max} \sim q_0 W/w$, where w is the width of a single dissolution
320 channel or wormhole. These observations suggest that the aspect ratio of
321 the fracture and its orientation with respect to the flow may also play an im-
322 portant role in determining the breakthrough time. If $W \geq L$ the drainage
323 basin is large and breakthrough will be rapid (as in the video), but if $W \ll L$
324 the flow focusing may stall with the dissolution front far from the outlet; in
325 this case breakthrough will be dependent on reaction kinetics.

326 Discrete fracture networks are widely used in reservoir modeling (Long et al.,
327 1982; Siemers and Dreybrodt, 1998) and in the assessment of dam safety (Dreybrodt et al.,
328 2002; Romanov et al., 2003), because they provide an effective means to de-
329 scribe localized regions of high permeability. However, each fracture within
330 the network is modeled at the one-dimensional level, and the possibility of
331 spatially localized dissolution within an individual fracture in the network is
332 not taken into account. In fractured carbonates an instability in the disso-
333 lution front can reduce the breakthrough time in an individual fracture by
334 orders of magnitude, thereby completely changing the hydraulic properties
335 of the global fracture network. It is therefore important to develop a model
336 of evolving fracture permeability that includes the inherent heterogeneity of
337 the dissolution process. Although the initial wavelength of the developing
338 instability is controlled by the reaction kinetics and flow rate, interactions
339 between the developing channels play the dominant role in the long-time evo-
340 lution of the fracture aperture field. Water throughout most of the fracture
341 is saturated with calcium ions; only in the narrow regions formed by the
342 active channels is there any significant undersaturation. Thus, an adequate
343 understanding of how single channels advance (Fig. 4 and video) would open
344 up the possibility of new field-scale models of fracture dissolution, describing
345 the growth of individual channels coupled together by long-range pressure
346 fields. This could make it feasible to include heterogeneous dissolution of
347 individual fractures in reservoir modeling, since the pressure fields around
348 long thin channels can be rapidly calculated using techniques of conformal
349 mapping (Gubiec and Szymczak, 2008).

350 Our analysis differs from previous work on instabilities in porous me-
351 dia (Chadam et al., 1986; Sherwood, 1987; Hinch and Bhatt, 1990) in that
352 we take a time-dependent aperture as the base state, rather than a propagat-
353 ing one-dimensional dissolution front. In a porous rock all the soluble ma-
354 terial eventually dissolves and therefore a time-independent porosity profile
355 can steadily advance into the material. However, in a fracture the aperture
356 profile evolves along the whole length, with an effectively unlimited increase
357 in aperture near the inlet.

358 **6. Conclusions**

359 The main conclusion from this work is that the dissolution of a single frac-
360 ture is inherently two-dimensional; the one-dimensional solutions frequently
361 used in models of cave formation (Dreybrodt, 1996) are unstable to infinites-
362 imal perturbations. This means that the kinetic trigger mechanism is not
363 a prerequisite for the development of long conduits. Although the develop-
364 ment of instabilities in fracture dissolution has been demonstrated by nu-
365 merical simulation (Hanna and Rajaram, 1998; Cheung and Rajaram, 2002;
366 Szymczak and Ladd, 2006, 2009), this is the first time, to our knowledge,
367 that the equations for fracture dissolution have been shown mathematically
368 to have unstable solutions. We have further shown that the instability devel-
369 ops with a well-defined wavelength, which depends on reaction kinetics and
370 flow rate but is insensitive to the initial roughness of the fracture. Subse-
371 quently, the localized regions of dissolution advance in the fracture in ways
372 that may eventually be understood in terms of modified models of Laplacian
373 growth.

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379 **Appendix A. Simulation method**

380 The depth-averaged equations, Eq. (8), were solved on a uniform grid
381 with a resolution of 1cm; further grid refinement did not affect the results

382 significantly. Periodic boundary conditions were imposed in the lateral (y)
 383 direction, while the inlet and outlet conditions were the same as in the one-
 384 dimensional case, Sec. 2.1. We included Taylor dispersion in the axial diffu-
 385 sion, $D_{xx} = D + q_x^2/210D$, but its effect on the erosion rate was negligible;
 386 in the lateral direction we took $D_{yy} = D$. One-dimensional calculations used
 387 the same code, but with a single grid point in the lateral (y) direction.

388 Calcite dissolution kinetics are more properly expressed in terms of the
 389 calcium ion concentration at the fracture surface, c_s , rather than the bulk
 390 concentration as in Eq. (6):

$$R(c_s) = \begin{cases} k(c_{sat} - c_s), & c_s < c_{th} \\ k_n(c_{sat} - c_s)^n, & c_s > c_{th}, \end{cases} \quad (\text{A.1})$$

391 The question then is how to relate the surface concentration, c_s , to the bulk
 392 concentration, c ; for this we must consider how diffusion limits the rate of
 393 mass transfer to the fracture surface. Diffusive transport of reactant across
 394 the fracture aperture can be approximated using an effective mass transfer
 395 coefficient or Sherwood number (Bird et al., 2001),

$$R_{diff} = \frac{D \text{Sh}}{2h}(c_s - c). \quad (\text{A.2})$$

396 The Sherwood number, Sh , depends on reaction rate but the variation is rela-
 397 tively small (Hayes and Kolaczkowski, 1994; Gupta and Balakotaiah, 2001),
 398 bounded by two asymptotic limits: constant flux, where $\text{Sh} = 8.24$, and
 399 constant concentration, where $\text{Sh} = 7.54$. In the numerical calculations we
 400 used the approximate value $\text{Sh} = 8$.

401 In sufficiently narrow apertures dissolution kinetics are reaction limited,
 402 $R \ll R_{diff}$, and $c_s \approx c$ which gives the reactive flux in Eq. (4). However, as
 403 the fracture opens the reaction rate becomes hindered by diffusive transport
 404 of reactant across the aperture. Finally, for $kh/DSh \ll 1$, the dissolution
 405 can become entirely diffusion limited, $R_{diff} \ll R$. In that case the surface
 406 concentration approaches that of a saturated solution $c_s \approx c_{sat}$ and

$$R_{diff} = \frac{D \text{Sh}}{2h}(c_{sat} - c). \quad (\text{A.3})$$

407 Thus the reactive flux is again of the form of Eq. (4) but with an effective rate
 408 constant $k_D = D \text{Sh}/2h$. Weyl (1958) assumed diffusion-limited kinetics, but
 409 for a typical fracture aperture (10^{-2} cm) k_D is 1–2 orders of magnitude larger

410 than k . In fact reaction-limited kinetics persist, with small modifications
 411 from the effects of diffusion, up until fracture apertures of the order of 1cm.

412 An effective reaction rate, including the effects of diffusion, can be ob-
 413 tained by balancing the reactive flux, R , with the diffusive flux, R_{diff} (Szymczak and Ladd,
 414 2009);

$$\frac{D \text{Sh}}{2h}(c_s - c) = R(c_s). \quad (\text{A.4})$$

415 In the case of linear kinetics we obtain an effective rate constant

$$k_{eff} = \frac{k}{1 + (2kh/D \text{Sh})}, \quad (\text{A.5})$$

416 which is valid for all apertures. For more reactive materials, such as gypsum,
 417 transport corrections are important, even for narrow apertures. In some cases
 418 the kinetics is entirely transport limited, as in Eq. (A.3)

419 In the most general case, non-linear kinetics combined with diffusion lim-
 420 ited mass transfer, we can combine Eqs. (A.1) and (A.4) to obtain the re-
 421 active flux in terms of the bulk concentration c . Defining the dimensionless
 422 quantities:

$$C = \frac{c_{sat} - c}{c_{sat} - c_{th}}, \quad C_s = \frac{c_{sat} - c_s}{c_{sat} - c_{th}}, \quad \alpha = \frac{2kh}{D \text{Sh}}, \quad (\text{A.6})$$

423 Eq. (A.4) becomes

$$\alpha C_s^m + C_s - C = 0, \quad (\text{A.7})$$

424 where C is known and C_s is to be found. The numerical simulations use
 425 Eq. (A.7), but the instability analysis (Sec. 3) assumes reaction-limited ki-
 426 netics, Eq. (6). The difference is small during the initial stages of calcite
 427 dissolution.

428 We used a flux-conserving discretization to solve for the pressure field,
 429 which avoids “numerical saturation” (Groves and Howard, 1994; Hanna and Rajaram,
 430 1998), even when the grid is relatively coarse. The scalar fields, aperture,
 431 pressure, and concentration are defined at the nodal points and gradients
 432 of the scalar fields are then naturally calculated on the edges of the cells
 433 surrounding each node. The divergence of the flux is then automatically cal-
 434 culated at the nodal position. However, the convective flux of reactant was
 435 calculated by upwind differencing to ensure stability.

436 The linear equations for the pressure field were solved using the MUMPS
 437 package (Amestoy et al., 2001, 2006), and the fluid volume flux was then
 438 calculated by differencing. For linear reaction kinetics, the concentration field

439 can be solved directly, but for non-linear kinetics Newton-Raphson iteration
 440 was employed, using MUMPS to solve the linear system at each step. Within
 441 each iteration of the bulk concentration field, the surface concentrations,
 442 Eq. (A.7), must be determined iteratively as well. The transition between
 443 linear ($C_s \geq 1$) and non-linear ($C_s < 1$) kinetics corresponds to $C = 1 +$
 444 α , and thus the appropriate branch of Eq. (A.1), can be identified from
 445 the bulk concentration. Once the concentration field has converged, the
 446 aperture field is updated based on the local erosion flux, $2R(c)$. We used
 447 an explicit midpoint method to determine the time evolution of the aperture
 448 field, requiring two complete cycles of the concentration solver at each time
 449 step.

450 **Appendix B. Transport and reaction parameters in typical frac-** 451 **tures**

452 Fracture apertures are between 0.005cm and 0.1cm (Motyka and Wilk,
 453 1984; Paillet et al., 1987; Dreybrodt, 1996), and hydraulic gradients are of
 454 the order of 10^{-3} to 10^{-1} (Palmer, 1991; Dijk and Berkowitz, 1998). This
 455 gives a range of characteristic flow velocities in undissolved fractures from
 456 10^{-4}cms^{-1} to 1cms^{-1} . The corresponding Péclet numbers are $0.05 < \text{Pe} <$
 457 10^4 , taking the solute diffusion coefficient $D = 10^{-5}\text{cm}^2\text{s}^{-1}$. The dissolution
 458 rate for limestone is usually in the range $10^{-5}\text{cms}^{-1} - 10^{-4}\text{cms}^{-1}$ (Palmer,
 459 1991; Dreybrodt, 1996), which leads to the Damköhler numbers in the range
 460 $10^{-5} < \text{Da} < 1$. Thus in most calcite fractures the parameter Pe^{-1}Da is
 461 small and the diffusive flux can be neglected, as in Sec. 3. Diffusion plays a
 462 more prominent role in dissolution of fractured gypsum, where the reaction
 463 rates are of the order of 0.01cms^{-1} (Jeschke et al., 2001), and thus Pe^{-1}Da
 464 is 2 – 3 orders of magnitude larger than in limestone systems.

465 **Appendix C. Linear stability analysis**

466 Equation (9) can be non-dimensionalized by scaling length by the pene-
 467 tration length, $x \rightarrow 2kx/q_0$, and time by the time taken to double the initial
 468 inlet aperture, $t \rightarrow 2ktc_{sat}/h_0c_{sol}$. It will be convenient to rewrite the con-
 469 centration field as a normalized undersaturation, $c \rightarrow (c_{sat} - c)/c_{sat}$. Then,
 470 scaling the remaining variables ($h, \mathbf{q}, \nabla p$) by their (constant) initial values

471 (h_0, q_0, p'_0) , we can rewrite Eq. (9) in dimensionless form,

$$\begin{aligned} \nabla \cdot \mathbf{q} &= 0, & \mathbf{q} &= h^3 \nabla p, \\ \mathbf{q} \cdot \nabla c &= -c, & \partial_t h &= c. \end{aligned} \quad (\text{C.1})$$

472 The one-dimensional solution of (C.1) is taken as the base state: $h_b(x, t) =$
 473 $1 + te^{-x}$, $\mathbf{q}_b = \hat{\mathbf{x}}$, and $c_b = e^{-x}$, where $\hat{\mathbf{x}}$ indicates a unit vector pointing in the
 474 x direction. We consider perturbations about the base state, $c = c_b + \delta c$; $h =$
 475 $h_b + \delta h$ etc. and keep just the linear terms:

$$\begin{aligned} \nabla \cdot \delta \mathbf{q} &= 0, & \delta \mathbf{q} &= 3h_b^{-1} \delta h \hat{\mathbf{x}} + h_b^3 \nabla \delta p, \\ \delta q_x \partial_x c_b + \partial_x \delta c &= -\delta c, & \partial_t \delta h &= \delta c. \end{aligned} \quad (\text{C.2})$$

476 The pressure variation can be eliminated from the equations for the vol-
 477 ume flux by cross differentiation,

$$\partial_y \delta q_x - \partial_x \delta q_y = 3h_b^{-1} (\partial_y \delta h - h'_b \delta q_y). \quad (\text{C.3})$$

478 where $h'_b = \partial_x h_b$ is the spatial derivative of the base aperture field. Com-
 479 bining this equation with the incompressibility equation, $\partial_y \delta q_y = -\partial_x \delta q_x$
 480 eliminates δq_y as well,

$$(\partial_x^2 + \partial_y^2) \delta q_x = 3h_b^{-1} (\partial_y^2 \delta h + h'_b \partial_x \delta q_x). \quad (\text{C.4})$$

481 Finally, rewriting the transport equation from (C.2) in the form $\delta q_x =$
 482 $\partial_x (e^x \delta c)$ and substituting into (C.4) leads to equations for the linearized
 483 variations in the concentration and aperture fields,

$$[h_b(\partial_x^2 + \partial_y^2) - 3h'_b \partial_x] \partial_x (e^x \delta c) = 3\partial_y^2 \delta h, \quad \partial_t \delta h = \delta c. \quad (\text{C.5})$$

484 We now examine the stability of a periodic perturbation in the aperture
 485 and concentration fields;

$$\delta h = g(x, t) e^{-x} \sin(uy), \quad \delta c = \partial_t g(x, t) e^{-x} \sin(uy), \quad (\text{C.6})$$

486 where the (dimensionless) wavevector $u = 2\pi l_p / \lambda$ and λ is the wavelength of
 487 the perturbation. This *ansatz* satisfies Eq. (C.5) provided that

$$[h_b(\partial_x^2 - u^2) - 3h'_b \partial_x] \partial_t \partial_x g + 3u^2 e^{-x} g = 0. \quad (\text{C.7})$$

488 In addition to the boundary condition $g(0, t) = 0$, there are boundary condi-
 489 tions from the uniformity of the flow across the inlet and outlet, $\delta q_y(0, y, t) =$
 490 $\delta q_x(x \rightarrow \infty, y, t) = 0$, or

$$\partial_x^2 g(0, t) = 0, \quad \partial_x g(x \rightarrow \infty, t) = 0. \quad (\text{C.8})$$

491 Equation (C.7) does not have an eigensolution because of the time-dependent
 492 base state (Tan and Homsy, 1986), but a numerical solution of Eq. (C.7) is
 493 shown as the solid line in the inset to Fig. 9. Further analytic progress can be
 494 made by freezing the base state at a particular instant of time, t_0 , replacing
 495 $h_b(x, t)$ by $h_b(t_0) = 1 + t_0 e^{-x}$ where t_0 is then kept constant:

$$[h_b(t_0)(\partial_x^2 - u^2) - 3h'_b(t_0)\partial_x] \partial_t \partial_x g + 3u^2 e^{-x} g = 0. \quad (\text{C.9})$$

496 In this case an eigensolution can be found of the form

$$g(x, t) = \hat{g}(x) e^{\omega t}, \quad (\text{C.10})$$

497 which gives an ordinary differential equation for \hat{g} ,

$$[h_b(t_0)(\partial_x^2 - u^2) - 3h'_b(t_0)\partial_x] \partial_x \hat{g} + 3\omega^{-1} u^2 e^{-x} \hat{g} = 0. \quad (\text{C.11})$$

498 Here we present the solution for the simplest case, $t_0 = 0$, for which $h_b(0) = 1$
 499 and $h'_b(0) = 0$. A similar but more complex solution can be obtained for
 500 arbitrary t_0 and results are shown in Fig. 9.

501 The general solution of Eq. (C.11) with $t_0 = 0$ is

$$\begin{aligned} \hat{g}(x) = & A {}_0F_2(1 + u, 1 - u; 3\omega^{-1} u^2 e^{-x}) \\ & + B e^{ux} {}_0F_2(1 + u, 1 - 2u; 3\omega^{-1} u^2 e^{-x}) \\ & + C e^{-ux} {}_0F_2(1 + u, 1 + 2u; 3\omega^{-1} u^2 e^{-x}), \end{aligned} \quad (\text{C.12})$$

502 where A , B , and C are constants and ${}_0F_2(p, q; z)$ is a generalized hypergeo-
 503 metric function. The far field boundary condition $\partial_x \hat{g}(x \rightarrow \infty) = 0$ requires
 504 that $B = 0$, while the condition $\hat{g}(0) = 0$ is then sufficient to determine the
 505 function $\hat{g}(x)$ to within an arbitrary constant, which is the initial amplitude
 506 of the perturbation. Imposing the final boundary condition, $\partial_x^2 \hat{g}(0) = 0$,

507 gives a dispersion relation for $\omega(u)$,

$$\begin{aligned}
& \left[\omega^2 {}_0\tilde{F}_2(1+u, 1+2u; 3\omega^{-1}u^2) + \right. \\
& \quad 3(1+2u)\omega {}_0\tilde{F}_2(2+u, 2+2u; 3\omega^{-1}u^2) \\
& \quad \left. + 9u^2 {}_0\tilde{F}_2(3+u, 3+2u; 3\omega^{-1}u^2) \right] {}_0\tilde{F}_2(1+u, 1-u; 3\omega^{-1}u^2) = \\
& \quad 3 \left[\omega {}_0\tilde{F}_2(2+u, 2-u; 3\omega^{-1}u^2) + \right. \\
& \quad \left. 3u^2 {}_0\tilde{F}_2(3+u, 3-u; 3\omega^{-1}u^2) \right] {}_0\tilde{F}_2(1+u, 1+2u; 3\omega^{-1}u^2), \quad (\text{C.13})
\end{aligned}$$

508 where ${}_0\tilde{F}_2(p, q; z) = {}_0F_2(p, q; z)/\Gamma(p)\Gamma(q)$. The maximum growth rate (largest
509 positive root) at each u from Eq. (C.13) is plotted in Fig. 5.

510 The derivation of the dispersion relation can be generalized to include
511 lateral diffusion (in the y direction). The convection-diffusion equation, in-
512 cluding lateral diffusion and scaled in the same way as Eq. (C.2), contains a
513 single parameter, the product $\text{Pe}^{-1}\text{Da} = Dkh_0/q_0^2$,

$$\partial_x(e^x\delta c) - (2\text{Pe}^{-1}\text{Da})\partial_y^2(e^x\delta c) = \delta q_x. \quad (\text{C.14})$$

514 The analogous linear stability analysis leads to the generalization of Eq. (C.11)
515 for finite diffusion. Simplifying to the case $t_0 = 0$,

$$[(u^2 - \partial_x^2) [\partial_x + (2\text{Pe}^{-1}\text{Da})u^2] \hat{g} - 3\omega^{-1}u^2 e^{-x} \hat{g} = 0. \quad (\text{C.15})$$

516 which can again be solved in terms of hypergeometric functions. The inset
517 to Fig. 5 shows the dispersion relation for several different values of the ratio
518 Pe^{-1}Da .

519 At long wavelengths the growth rate is linear in the wavevector, $\omega \rightarrow 3u$,
520 while for small wavelengths an asymptotic analysis, including lateral diffu-
521 sion, gives $\omega \rightarrow 3\text{Pe}\text{Da}^{-1}u^{-2}$. However, the convective limit (no diffusion)
522 appears to be singular, with $\omega \sim u^{-1}$ at large u .

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